

# Introduction to H.264

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November 22, 2002

## Outline

- History of video coding standards
- Overview of H.264
- Selected new features in H.264
  - Video coding
    - \* Integer transform
    - \* Intra prediction
    - \* De-blocking filter
  - Error resilience
    - \* Multiple frame prediction
    - \* SP/SI frame
- Performance of H.264

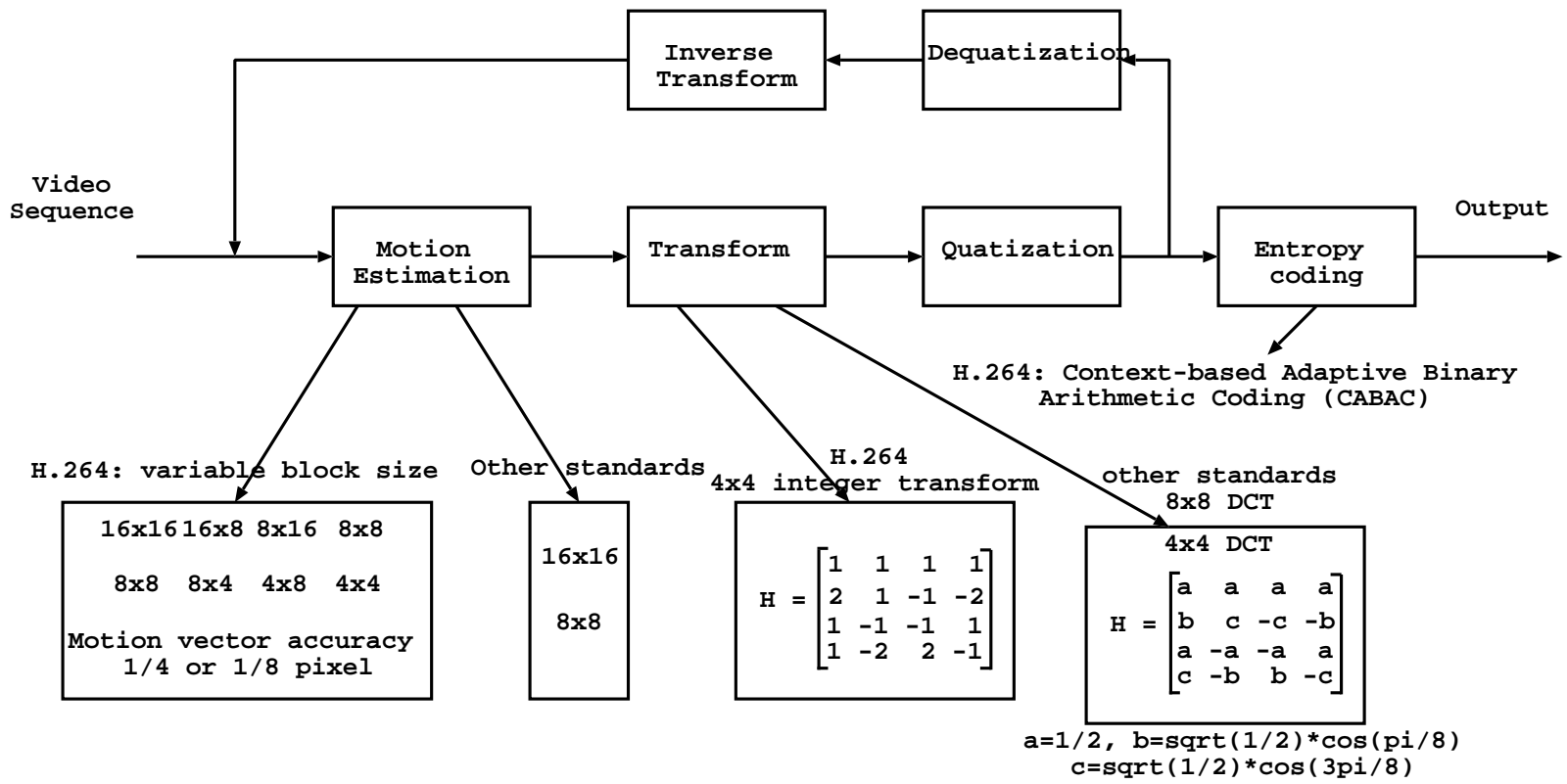
# History of Video Coding Standards

- ITU-T Video Coding Experts Group (VCEG)
  - H.261 (1990) → H.263 (1995) → H.263+ (1998) → H.26L
- ISO Motion Picture Experts Group (MPEG)
  - MPEG1(1991) → MPEG2 (1994) → MPEG4 (1999)
- Joint Video Team (JVT) (VCEG/MPEG) 2001
  - H.264/MPEG4 part 10. Official title: Advanced Video Coding (AVC)
  - International standard: December 2002

## Overview of H.264

- Video coding is similar in spirit to other standards but with important differences
- Key new features:
  - Enhanced motion estimation with variable block size
  - Integer block transform
  - Improved in-loop deblocking filter
  - Enhanced entropy coding
- Average bit rate reduction of 50% given fixed fidelity compared to any other standard
- Complexity vs. Coding efficiency

# Video Coding System



# Integer Transform

- Motivation
  - Quantization reduces precision
  - Small block size (4x4) reduces the performance loss
- Discrete Cosine Transform (DCT) has been used widely in standards
  - Good energy compact property
  - Orthogonal bases

## From DCT to Integer Transform

$$Y = AXA^T = \begin{bmatrix} a & a & a & a \\ b & c & -c & -b \\ a & -a & -a & a \\ c & -b & b & -c \end{bmatrix} X \begin{bmatrix} a & b & a & c \\ a & c & -a & -b \\ a & -c & -a & b \\ a & -b & a & -c \end{bmatrix}$$

$$Y = (CXC^T) \oplus E = (CXC^T) \oplus \begin{bmatrix} a^2 & ab & a^2 & ab \\ ab & b^2 & ab & b^2 \\ a^2 & ab & a^2 & ab \\ ab & b^2 & ab & b^2 \end{bmatrix}$$

- where  $C = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & d & -d & -1 \\ 1 & -1 & -1 & 1 \\ d & -1 & 1 & -d \end{bmatrix}$

- $a = 1/2, b = \sqrt{1/2} \cos \pi/8, c = \sqrt{1/2} \cos 3\pi/8, d = c/b \approx 0.414$

## Make the Integer Transform Orthogonal

- To make the transform simple, we approximate  $d$  with  $1/2$
- To maintain orthogonality, modify  $b$  to  $b = \sqrt{2/5}$
- Now the transform becomes

$$Y = (HXH^T) \oplus \begin{bmatrix} a^2 & ab & a^2 & ab \\ ab & b^2 & ab & b^2 \\ a^2 & ab & a^2 & ab \\ ab & b^2 & ab & b^2 \end{bmatrix}$$

- where  $H = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1/2 & -1/2 & -1 \\ 1 & -1 & -1 & 1 \\ 1/2 & -1 & 1 & -1/2 \end{bmatrix}$ ,  $b = \sqrt{2/5}$



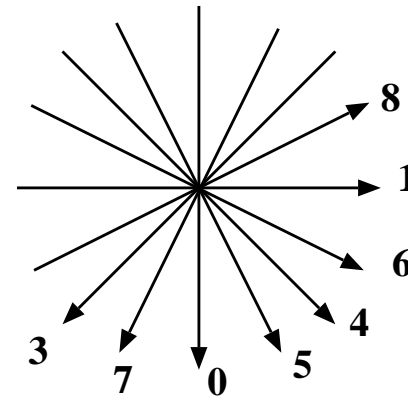
## Performance of Integer Transform

- Scenario: Stationary Gauss-Markov input with correlation coefficient  $\rho = 0.9$ 
  - Coding gain for  $H$ :  $5.38dB$ , Coding gain for DCT:  $5.39dB$
- Video compression: input are prediction residuals,  $\rho < 0.9$

# Intra Prediction

- Directional spatial prediction

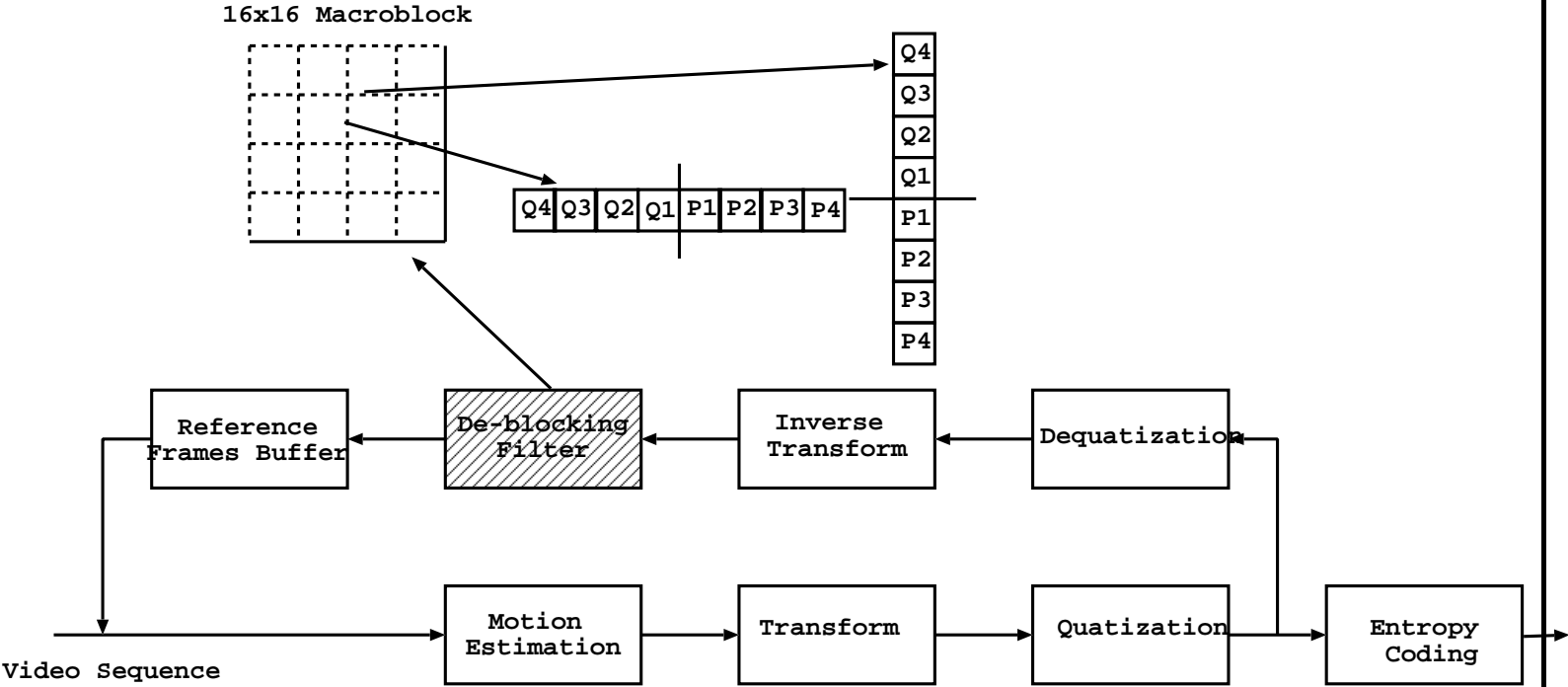
M	A	B	C	D	E	F	G	H
I	a	b	c	d				
J	e	f	g	h				
K	i	j	k	l				
L	m	n	o	p				



- 9 optional prediction modes
- $a - p$  is predicted from  $A - M$
- For example:  $a = (A + 2M + I + 2)/4$  (Mode 3)

# De-blocking Filter

- Motivation: Reduce blocking artifacts



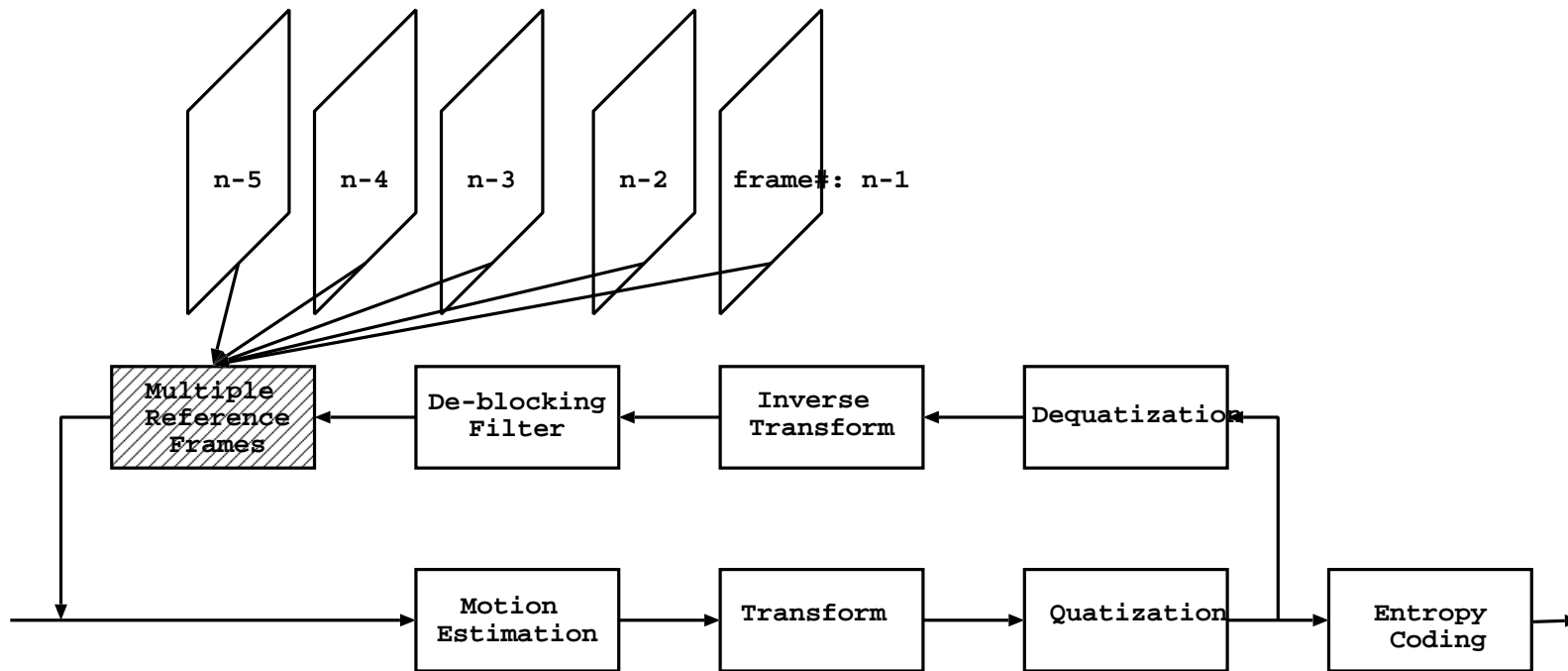
## De-blocking Filter (Cont.)

- Improves subjective visual quality of the decoded picture.
- Much better than post filtering.
- Highly content adaptive filtering
  - On edge level, filtering strength is dependent on the code mode, motion vector, and values of residuals
  - On sample level, quantizer dependent thresholds can turn off filtering for any individual sample

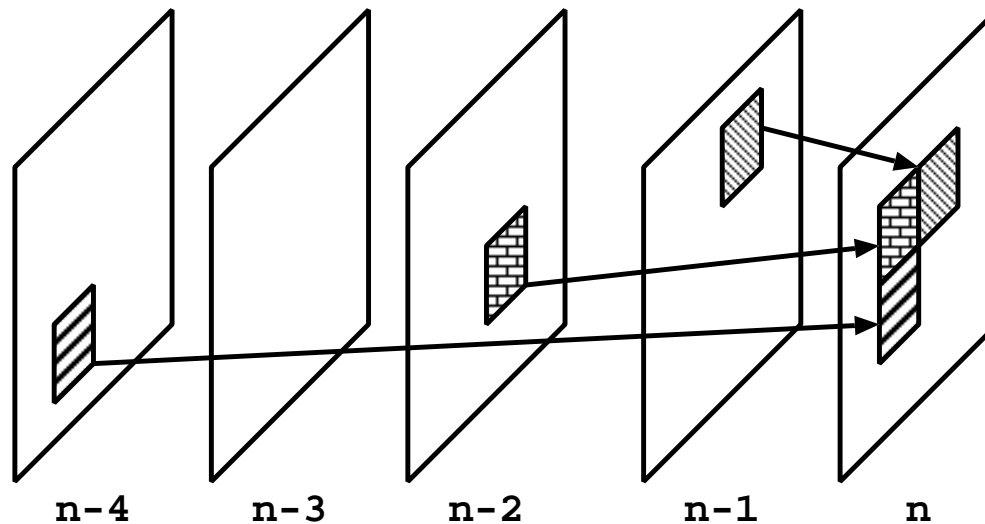
## **Error Resilience Features in H.264**

- **Multiple reference frames**
- **SP/SI frames**
- Slice structured coding
- Data partitioning
- Intra frame or intra microblock updates

# Multiple Reference Frames



## A Scenario using Multiple Reference Frames

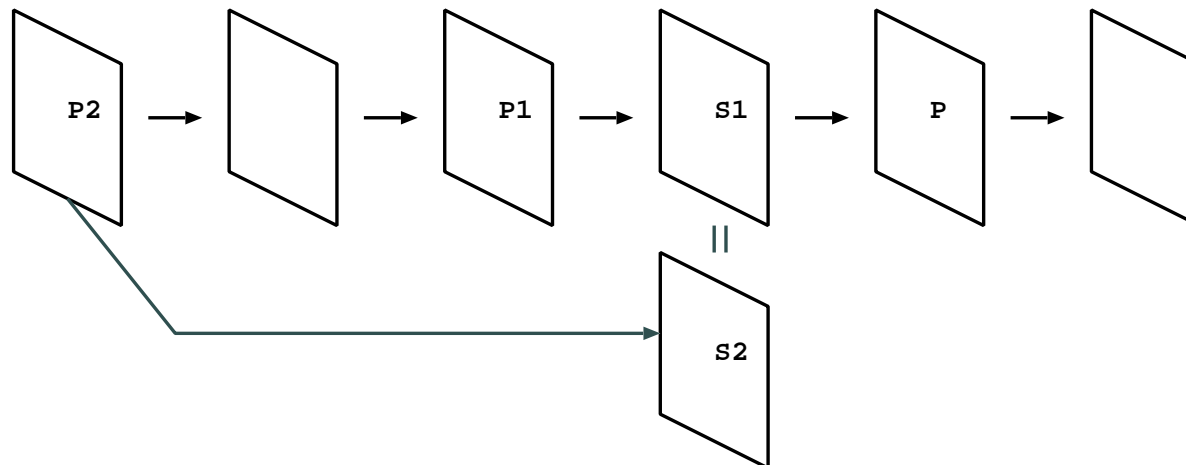


- Improve the performance of motion estimation
- Solve the uncovered background problem
- Increase the coding and decoding complexity
- Increase the size of reference frames buffer

# S Frame

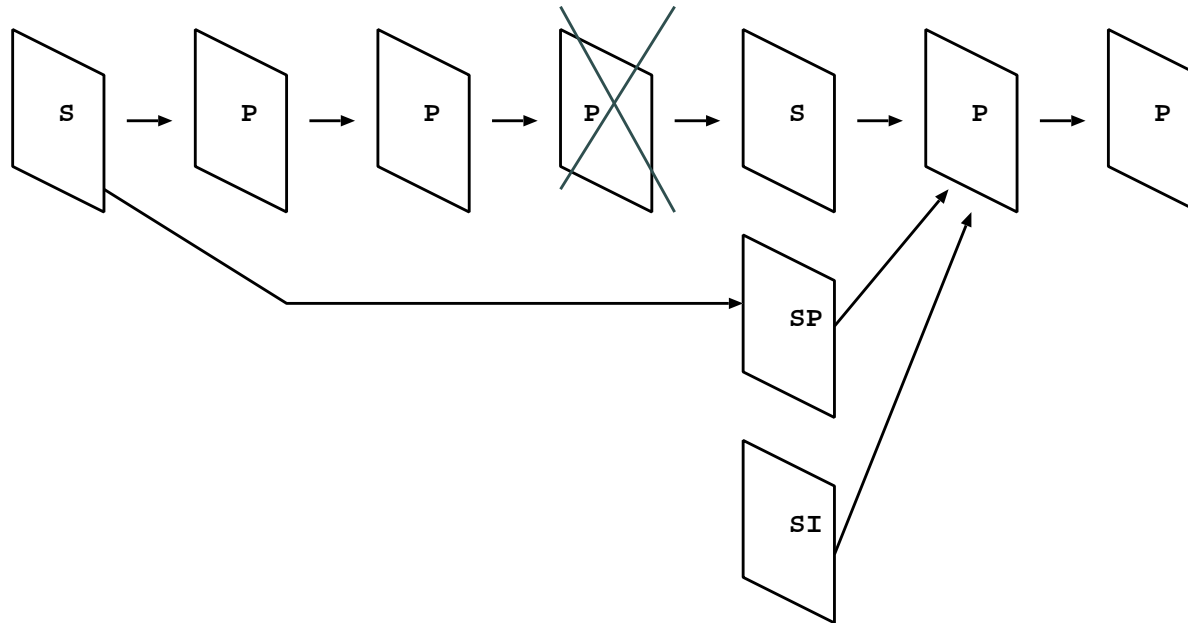
- Idea

- Reconstruct identical frame even when different reference frames were used



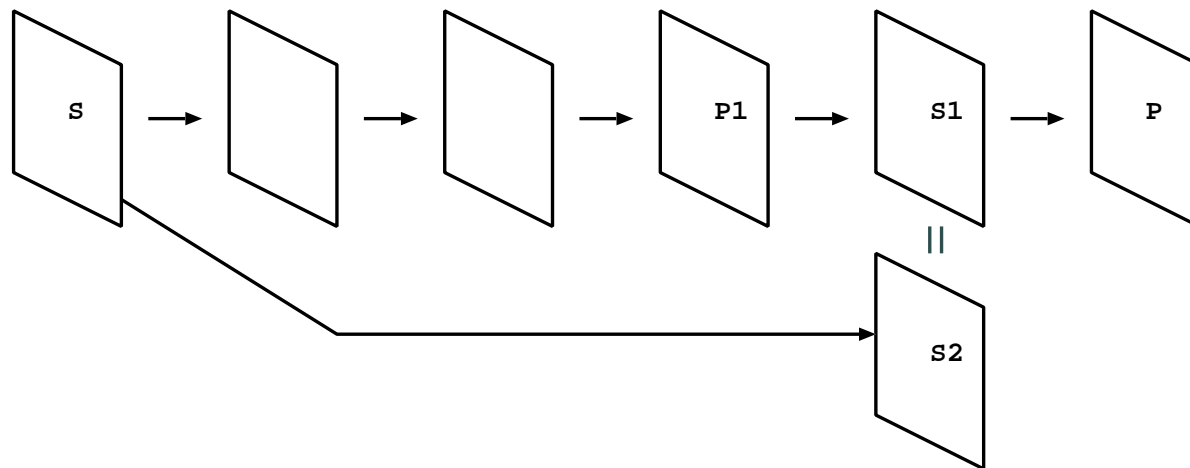


## S Frame in Error Resilience



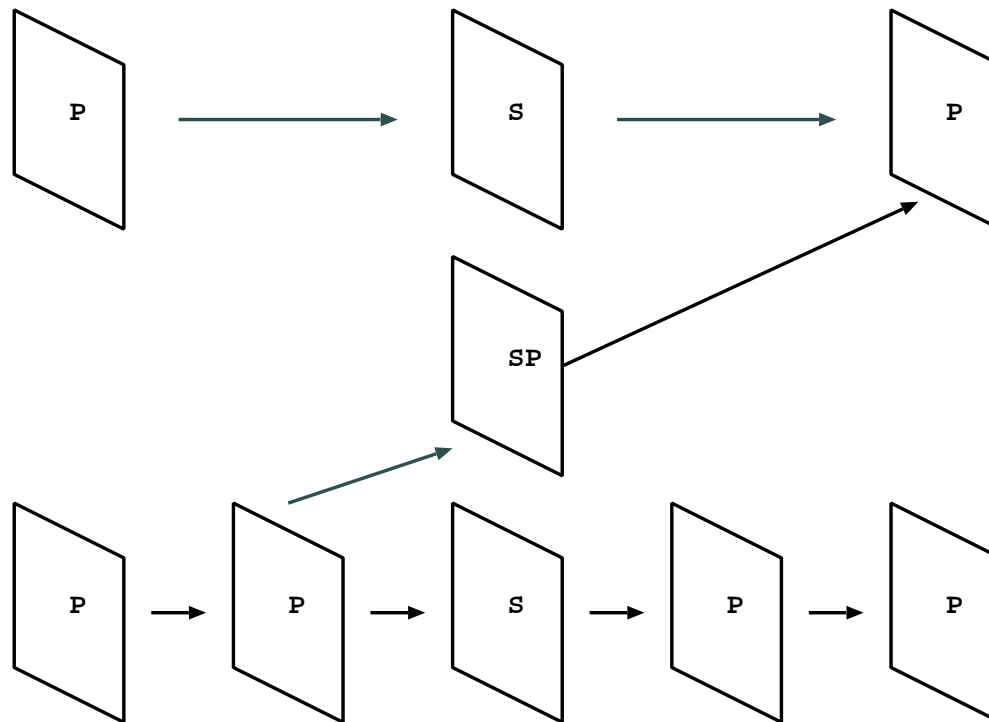
- Only one of S/SP/SI frames will be sent
- SP frame will be sent when its reference frame is available
- Problem: S/SP/SI will be used as reference frame for the following frames, how to make them identical?

## How S Frame Works



- $S_1 = L_{pred1} + L_{err1}$ ,  $S_2 = L_{pred2} + L_{err2}$
- To make  $S_1 = S_2$ , we have
  - $L_{err2} = S_1 - L_{pred2}$

## S Frame in Fast Forward



- SP frame will be sent only during bitstream switching
- More efficient than using I frame

## Performance of H.264

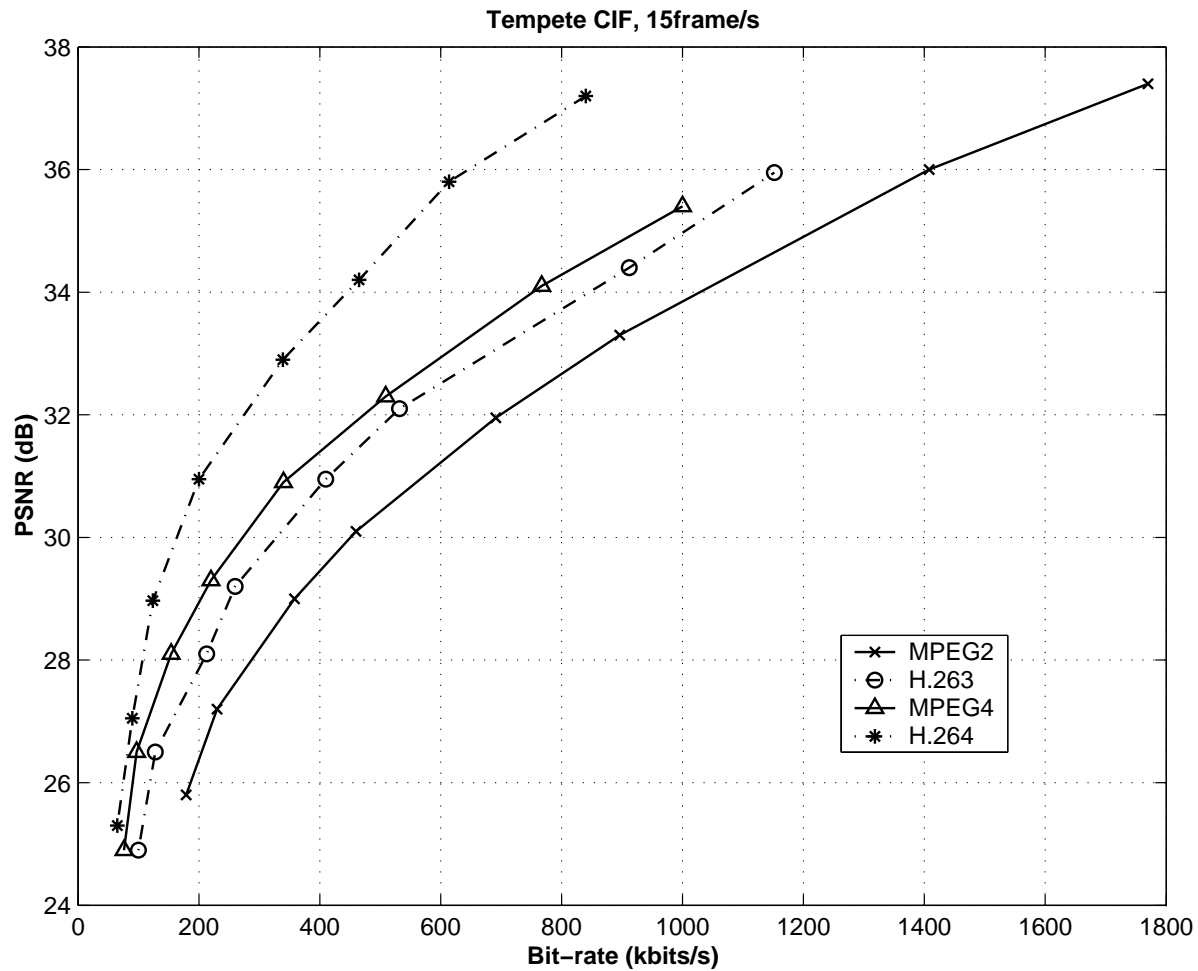
- Results from [3]
- Using same rate-distortion optimization techniques for all codecs
- Several video sequences for each test
- Compare four codecs:
  - MPEG2
  - H.263 (baseline profile)
  - MPEG4 (simple profile)
  - H.264

## Rate Saving Compare to Other Standards

Table 1: Average rate savings compare to other standards

Codec	MPEG4	H.263	MPEG2
H.264	39%	49%	64%
MPEG4	-	17%	43%
H.263	-	-	31%

# Performance Comparison



## Reference

1. Special session of H.26L, ICIP 2002
2. Ftp site: <http://bs.hhi.de/~suehring/tml/>
3. The Emerging JVT/H.26L Video Coding Standards,  
Proceeding of IBC 2002, Amsterdam, NL, Sept. 2002