

[Help](#)

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#include "bs2d_std2d.h"

static int Psor(int am,double s1,double s2,
    NumFunc_2 *p,double t,double r,double divid1,double
    divid2,double sigma1,double sigma2,double rho,int
    N, int M,double omega,double epsilon,double *ptpr
    ice,double *ptdelta1,double *ptdelta2)
{
    int TimeIndex,j,i,Index,n;
    double x1,x2,m1,m2,cov;
    double limit1,limit2,h1,h2;
    double a2,b2,c2,d2,e2,f2,g2,i2,j2;
    double k,y;
    double **P,**G,**Obst;
    double error,norm;
    int loops;

    /*Memory Allocation*/
    P=(double **)calloc(N+1,sizeof(double *));
    if (P==NULL)
        return MEMORY_ALLOCATION_FAILURE;
    for (i=0;i<N+1;i++)
    {
        P[i]=(double *)calloc(N+1,sizeof(double));
        if (P[i]==NULL)
            return MEMORY_ALLOCATION_FAILURE;
    }
    G=(double **)calloc(N+1,sizeof(double *));
    if (G==NULL)
        return MEMORY_ALLOCATION_FAILURE;
    for (i=0;i<N+1;i++)
    {
        G[i]=(double *)calloc(N+1,sizeof(double));
        if (G[i]==NULL)
            return MEMORY_ALLOCATION_FAILURE;
    }
    Obst=(double **)calloc(N+1,sizeof(double *));
    if (Obst==NULL)
        return MEMORY_ALLOCATION_FAILURE;
    for (i=0;i<N+1;i++)
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    {
        Obst[i]=(double *)calloc(N+1,sizeof(double)
    );
        if (Obst[i]==NULL)
return MEMORY_ALLOCATION_FAILURE;
    }

m1=(r-divid1)-SQR(sigma1)/2.0;
m2=(r-divid2)-SQR(sigma2)/2.0;
cov=rho*sigma1*sigma2;

/*Space Localisation*/
limit1=sigma1*sqrt(t)*sqrt(log(1/PRECISION))+fa
bs(m1)*t;
limit2=sigma2*sqrt(t)*sqrt(log(1/PRECISION))+fa
bs(m2)*t;

/*Space Step*/
h1=2.*limit1/(double) N;
h2=2.*limit2/(double)N;

/*Time Step*/
k=t/(double)M;

/*Lhs factor*/
a2=1.+k*(r+SQR(sigma1)/SQR(h1)+SQR(sigma2)/SQR(
h2));
b2=-k*(SQR(sigma1)/(2.*SQR(h1))+m1/(2.*h1));
c2=-k*(SQR(sigma1)/(2.*SQR(h1))-m1/(2.*h1));
d2=-k*(SQR(sigma2)/(2.*SQR(h2))+m2/(2.*h2));
e2=-k*(SQR(sigma2)/(2.*SQR(h2))-m2/(2.*h2));

f2=k*cov/(4.*h1*h2);
g2=k*cov/(4.*h1*h2);
i2=-k*cov/(4.*h1*h2);
j2=-k*cov/(4.*h1*h2);

/*Terminal Values*/
x1=log(s1);
x2=log(s2);

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for(i=0;i<=N;i++) {
    for (j=0;j<=N;j++) {
        Obst[i][j]=(p->Compute)(p->Par, exp(x1-limi
t1+h1*(double)j),
            exp(x2+limit2-h2*(double)i));
        P[i][j]=Obst[i][j];
    }
}

/*Finite Difference Cycle */
for (TimeIndex=1;TimeIndex<=M;TimeIndex++)
{
    for(i=1;i<N;i++)
for (n=1;n<N;n++)
    G[i][n]=P[i][n];

    /*Psor Cycle*/
    loops=0;
    do
    {
        error=0.;
        norm=0.;

        for(i=1;i<N;i++) {
            for(n=1;n<N;n++)
            {
                y=(G[i][n]-(c2*P[i][n-1]+b2*P[i][
n+1]+e2*P[i+1][n]+d2*P[i-1][n]+
                f2*P[i+1][n+1]+g2*P[i-1][n-1]+i2*P[
i+1][n-1]+
                j2*P[i-1][n+1]))/a2;
                y=P[i][n]+omega*(y-P[i][n]);

                /*Projection for American case*/
                if (am)
                    y=MAX(Obst[i][n],y);

                error+=fabs(y-P[i][n]);
                norm+=fabs(y);
                P[i][n]=y;
            }
        }
    }
}

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    }
    if (norm<1.0) norm=1.0;
    error=error/norm;
    loops++;
}
    while ((error>epsilon) && (loops<MAXLOOPS))
;
    /*End Psor Cycle*/
    /* printf("%d\n",loops);*/
}

Index=(int)((double)N/2.0);

/*Price*/
*ptprice=P[Index][Index];

/*Deltas*/
*ptdelta1=(P[Index][Index+1]-P[Index][Index-1])
/(2.*s1*h1);
*ptdelta2=(P[Index-1][Index]-P[Index+1][Index])
/(2.*s2*h2);

/*Memory desallocation*/
for (i=0;i<N+1;i++)
    free(P[i]);
free(P);

for (i=0;i<N+1;i++)
    free(G[i]);
free(G);

for (i=0;i<N+1;i++)
    free(Obst[i]);
free(Obst);

return OK;
}

int CALC(FD_Psor)(void *Opt,void *Mod,Pricing
    Method *Met)
{

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TYPEOPT* ptOpt=(TYPEOPT*)Opt;
TYPEMOD* ptMod=(TYPEMOD*)Mod;
double r,divid1,divid2;

r=log(1.+ptMod->R.Val.V_DOUBLE/100.);
divid1=log(1.+ptMod->Divid1.Val.V_DOUBLE/100.);
divid2=log(1.+ptMod->Divid2.Val.V_DOUBLE/100.);

return Psor(ptOpt->EuOrAm.Val.V_BOOL,ptMod->S01
.Val.V_PDOUBLE,
ptMod->S02.Val.V_PDOUBLE,ptOpt->PayOff.
Val.V_NUMFUNC_2,
ptOpt->Maturity.Val.V_DATE-ptMod->T.Val.
V_DATE,
r,divid1,divid2,ptMod->Sigma1.Val.V_PDOU
BLE,ptMod->Sigma2.Val.V_PDOUBLE,ptMod->Rho.Val.V_
RGDOUBLE,
Met->Par[0].Val.V_INT,Met->Par[1].Val.V_
INT,Met->Par[2].Val.V_RGDOUBLE,Met->Par[3].Val.V_RG
DOUBLE,
&(Met->Res[0].Val.V_DOUBLE),&(Met->Res[1
].Val.V_DOUBLE),&(Met->Res[2].Val.V_DOUBLE));
}

int CHK_OPT(FD_Psor)(void *Opt, void *Mod)
{
Option* ptOpt=(Option*)Opt;
TYPEOPT* opt=(TYPEOPT*)(ptOpt->TypeOpt);

return OK;
}

static int MET(Init)(PricingMethod *Met)
{
static int first=1;

if (first)
{
Met->Par[0].Val.V_INT2=100;
Met->Par[1].Val.V_INT2=100;
Met->Par[2].Val.V_RGDOUBLE12=1.5;

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        Met->Par[3].Val.V_RGDOUBLE=0.000001;
        first=0;
    }
    return OK;
}

PricingMethod MET(FD_Psor)=
{
    "FD_Psor",
    {"SpaceStepNumber",INT2,100,ALLOW},{"TimeStep
        Number",INT2,100,ALLOW}
        ,{"Omega",RGDOUBLE12,100,ALLOW},{"Epsilon",RG
        DOUBLE,100,ALLOW},{" ",END,0,FORBID}},
    CALC(FD_Psor),
    {"Price",DOUBLE,100,FORBID},{"Delta1",DOUBLE,1
        00,FORBID} ,
        {"Delta2",DOUBLE,100,FORBID} ,
        {" ",END,0,FORBID}},
    CHK_OPT(FD_Psor),
    CHK_ok,
    MET(Init)
};

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References