

Help

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/* Monte Carlo Simulation for Parisian option :
   The program provides estimations for Price and Delta with
   a confidence interval. */
/* Quasi Monte Carlo simulation is not yet allowed for this routine */

#include "bs1d_lim.h"

static int check_parisianin(double *gt, double lnspot, double lastlnspot,
                           double barrier, double lastbarrier,
                           double *gt_increment, double lnspot_increment, double lastlnspot_increment,
                           double rap, int upordown, double h, double time,
                           int *correction_active, int generator)
{
    double proba, uniform;

    if (((upordown==0)&&(lnspot<barrier))||((upordown==1)&&(lnspot>barrier)))
    {
        if (((lastlnspot>barrier)&&(upordown==1))||((lastlnspot<barrier)&&(upordown==0)))
        {
            proba=exp(-2.*rap*((lastlnspot-lastbarrier)*(lnspot-lastbarrier)-(lastlnspot-lastbarrier)*(barrier-lastbarrier)));
            *correction_active=1;
            uniform=Uniform(generator);
            if (uniform<proba)
                *gt=time;
        }
        else *gt=(time-h)+(barrier-lastlnspot)/(lnspot-lastlnspot)*h;
    }
}

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    }
    else *gt=time;

    if (((upordown==0)&&(lnspot_increment<barrier))
        ||((upordown==1)&&(lnspot_increment>barrier)))
    {
        if (((lastlnspot_increment>barrier)&&(upordown==1))||((lastlnspot_increment<barrier)&&(upordown==0)))
        {
            proba=exp(-2.*rap*((lastlnspot_increment-
            lastbarrier)*(lnspot_increment-lastbarrier)-(la
            stlnspot_increment-lastbarrier)*(barrier-lastbarri
            er)));
            if (!*correction_active)
                uniform=Uniform(generator);
            if (uniform<proba)
                *gt_increment=time;
        }
        else *gt_increment=(time-h)+(barrier-lastl
        nspot_increment)/(lnspot_increment-lastlnspot_inc
        rement)*h;
    }
    else *gt_increment=time;

    return OK;

}

static int MC_ParisianIn(int upordown,double s,
    NumFunc_1 *PayOff,double l,double t,double delay,
    double r,double divid,double sigma,int generator,long
    M,int N,double increment, double confidence,
    double *ptprice,double *ptdelta,double *pterror_price,
    double *pterror_delta,double *inf_price, double *sup_
    price, double *inf_delta, double *sup_delta)
{
    double g, h;
    double time,lnspot,lastlnspot,price_sample,delt
    a_sample,lns;
    double lnspot_increment,lastlnspot_increment,pr

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    ice_sample_increment;
double rloc,sigmaloc,barrier,lastbarrier,rap;
double gt,hd,gt_increment,hd_increment;
double mean_price,var_price,mean_delta,var_delta;
long i;
int k,inside,inside_increment;
int correction_active,dummy;
int init_mc, mc_or_qmc;
int simulation_dim;
double alpha, z_alpha;

/* Value to construct the confidence interval */
/
alpha= (1.- confidence)/2.;
z_alpha= Inverse_erf(1.- alpha);

/*One forces N if necessary so that delay
!!!!!!!!!! WARNING !!!!!!!!!!
be greater than the time step increment h*/
h=t/(double)N;
if (delay<=h)
{
    N=(int)ceil(t/delay)+1;
    h=t/(double)N;

    Fprintf(TOSCREEN,"WARNING!!! N is forced to
    %d\n",N);
}

/*Initialisation*/
mean_price=0.0;
mean_delta=0.0;
var_price=0.0;
var_delta=0.0;
/* Maximum Size of the random vector we need
in the simulation */
simulation_dim= N;

barrier=log(1);

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lns=log(s);

rloc=(r-divid-SQR(sigma)/2.)*h;
sigmaloc=sigma*sqrt(h);

/*Coefficient for the computation of the exit
  probability*/
rap=1./(sigmaloc*sigmaloc);

/*MC sampling*/
init_mc= InitGenerator(generator, simulation_
  dim,M);
/* Test after initialization for the generator
  */
if(init_mc == OK)
{
  mc_or_qmc= Rand_Or_Quasi(generator);

  /* Begin M iterations */
  for(i=1;i<=M;i++)
  {

    gt=0.;
    hd=0.;
    lnspot=lns;

    /*Inside=0 if the path stays beyond the
    barrier uninterruptedly
    for longer than delay*/
    inside=1;
    inside_increment=1;

    time=0;
    k=0;

    /*Barrier at time*/
    barrier=log(1);

    /*Simulation of i-th path until Inside=0*
    /
    while (((inside) && (k<N)) ||((inside_inc

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rement) && (k<N)))
{
    correction_active=0;

    lastlnspot=lnspot;
    lastbarrier=barrier;

    time+=h;
    g= Gaussians[mc_or_qmc](1, CREATE, 0,
generator);
    lnspot+=rloc+sigmaloc*g;

    lnspot_increment=lnspot+increment;
    lastlnspot_increment=lastlnspot+incre
ment;

    barrier=log(1);

    /*Check if the i-th path has reached
the barrier at time*/
    /*Otherwise there is no extinction*/
    if (upordown==0)
        dummy=check_parisianin(&gt,lnspot,la
stlnspot,barrier,lastbarrier,
                                &gt_increment,lnsp
ot_increment,lastlnspot_increment,
                                rap,upordown,h,
time,&correction_active,generator);
    else
        dummy=check_parisianin(&gt_increment,
lnspot_increment,lastlnspot_increment,barrier,la
stbarrier,&gt,lnspot,lastlnspot,rap,upordown,h,
time,&correction_active,generator);

    hd=time-gt;
    hd_increment=time-gt_increment;

    if(hd>delay)
    {
        inside=0;
        if (time>t) time=t;
    }

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        price_sample=exp(-r*time)*Boundary(
exp(lnspot),PayOff,t-time,r,divid,sigma);
    }

    if(hd_increment>delay)
    {
        inside_increment=0;
        if (time>t) time=t;
        price_sample_increment=exp(-r*time)
*Boundary(exp(lnspot_increment),PayOff,t-time,r,
divid,sigma);
    }

    k++;
}

if (inside)
price_sample=0.;

if (inside_increment)
price_sample_increment=0.;

/*Delta*/
delta_sample=(price_sample_increment-pric
e_sample)/(increment*s);

/*Sum*/
mean_price+= price_sample;
mean_delta+= delta_sample;

/*Sum of Squares*/
var_price+= SQR(price_sample);
var_delta+= SQR(delta_sample);
}

/* End N iterations */

/*Price*/
*ptprice=mean_price/(double)M;
*pterror_price= sqrt(var_price/(double)M -
SQR(*ptprice))/sqrt(M-1);

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        /*Delta*/
        if ( (PayOff->Compute)==&Put)
*ptdelta=-mean_delta/(double) M;
        if ( (PayOff->Compute)==&Call)
*ptdelta=mean_delta/(double) M;
        *pterror_delta= sqrt(var_delta/(double)M-SQ
R(*ptdelta))/sqrt((double)M-1);

        /* Price Confidence Interval */
        *inf_price= *ptprice - z_alpha*(*pterror_p
rice);
        *sup_price= *ptprice + z_alpha*(*pterror_p
rice);

        /* Delta Confidence Interval */
        *inf_delta= *ptdelta - z_alpha*(*pterror_d
elta);
        *sup_delta= *ptdelta + z_alpha*(*pterror_d
elta);
    }
    return init_mc;
}

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int CALC(MC_ParisianIn)(void *Opt,void *Mod,Pric
ingMethod *Met)
{
    TYPEOPT* ptOpt=(TYPEOPT*)Opt;
    TYPEMOD* ptMod=(TYPEMOD*)Mod;
    double r,divid,limit;
    int upordown;

    r=log(1.+ptMod->R.Val.V_DOUBLE/100.);
    divid=log(1.+ptMod->Divid.Val.V_DOUBLE/100.);
    limit=((ptOpt->Limit.Val.V_NUMFUNC_1)->Compute)
        ((ptOpt->Limit.Val.V_NUMFUNC_1)->Par,ptMod->T.
Val.V_DATE);

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if ((ptOpt->DownOrUp).Val.V_BOOL==DOWN)
    upordown=0;
else upordown=1;

return MC_ParisianIn(upordown,
    ptMod->S0.Val.V_PDOUBLE,ptOpt->
    PayOff.Val.V_NUMFUNC_1,
    limit,
    ptOpt->Maturity.Val.V_DATE-pt
    Mod->T.Val.V_DATE,
    (ptOpt->Limit.Val.V_NUMFUNC_1)-
    >Par[4].Val.V_PDOUBLE,
    r,
    divid,ptMod->Sigma.Val.V_PDOUBL
    E,
    Met->Par[1].Val.V_INT,
    Met->Par[0].Val.V_LONG,
    Met->Par[2].Val.V_INT,Met->Par[
    3].Val.V_PDOUBLE,
    Met->Par[4].Val.V_PDOUBLE,
    &(Met->Res[0].Val.V_DOUBLE),
    &(Met->Res[1].Val.V_DOUBLE),
    &(Met->Res[2].Val.V_DOUBLE),
    &(Met->Res[3].Val.V_DOUBLE),
    &(Met->Res[4].Val.V_DOUBLE),
    &(Met->Res[5].Val.V_DOUBLE),
    &(Met->Res[6].Val.V_DOUBLE),
    &(Met->Res[7].Val.V_DOUBLE));
}

int CHK_OPT(MC_ParisianIn)(void *Opt, void *Mod)
{
    Option* ptOpt=(Option*)Opt;
    TYPEOPT* opt=(TYPEOPT*)(ptOpt->TypeOpt);

    if ((opt->RebOrNo).Val.V_BOOL==NOREBATE)
        if ((opt->OutOrIn).Val.V_BOOL==IN)
            if ((opt->EuOrAm).Val.V_BOOL==EURO)

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        if ((opt->Parisian).Val.V_BOOL==OK)

            return OK;

    return  WRONG;
}

static int MET(Init)(PricingMethod *Met)
{
    static int first=1;
    int type_generator;

    type_generator= Met->Par[1].Val.V_INT;

    if (first)
    {
        Met->Par[0].Val.V_LONG=10000;
        Met->Par[1].Val.V_INT=0;
        Met->Par[2].Val.V_INT2=250;
        Met->Par[3].Val.V_PDOUBLE=0.01;
        Met->Par[4].Val.V_PDOUBLE= 0.95;

        first=0;
    }

    if(Rand_Or_Quasi(type_generator)==QMC)
    {
        Met->Res[2].Viter=IRRELEVANT;
        Met->Res[3].Viter=IRRELEVANT;
        Met->Res[4].Viter=IRRELEVANT;
        Met->Res[5].Viter=IRRELEVANT;
        Met->Res[6].Viter=IRRELEVANT;
        Met->Res[7].Viter=IRRELEVANT;

    }
    else
    {
        Met->Res[2].Viter=ALLOW;
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        Met->Res[3].Viter=ALLOW;
        Met->Res[4].Viter=ALLOW;
        Met->Res[5].Viter=ALLOW;
        Met->Res[6].Viter=ALLOW;
        Met->Res[7].Viter=ALLOW;
    }
    return OK;
}

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PricingMethod MET(MC_ParisianIn)=
{
    "MC_Parisianin",
    {"Iterations",LONG,100,ALLOW},
    {"RandomGenerator",GENER,100,ALLOW},
    {"TimeStepNumber",INT2,100,ALLOW},
    {"Delta Increment Rel",DOUBLE,100,ALLOW},
    {"Confidence Value",DOUBLE,100,ALLOW},
    {" ",END,0,FORBID}},
    CALC(MC_ParisianIn),
    {"Price",DOUBLE,100,FORBID},
    {"Delta",DOUBLE,100,FORBID} ,
    {"Error Price",DOUBLE,100,FORBID}
    ,{"Error Delta",DOUBLE,100,FORBID} ,
    {"Inf Price",DOUBLE,100,FORBID},
    {"Sup Price",DOUBLE,100,FORBID} ,
    {"Inf Delta",DOUBLE,100,FORBID},
    {"Sup Delta",DOUBLE,100,FORBID} ,
    {" ",END,0,FORBID}},
    CHK_OPT(MC_ParisianIn),
    CHK_mc_generator,
    MET(Init)
} ;

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References