

[Help](#)

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#include "bs1d_std.h"

static double *FP, *Paths=NULL, *NextPaths=NULL,
    *Res=NULL;
static double *M=NULL, *AuxR=NULL, *VBasis, *Brownian_Bridge=NULL, *Aux_BS=NULL;
static double (*Basis)(double *x, int i);
static int TsRoB_Allocation(long MC_Iterations,
    int DimApprox, int BS_Dimension)
{

    if (FP==NULL)
    FP=(double*)malloc(MC_Iterations*sizeof(
        double));
    if (FP==NULL) return MEMORY_ALLOCATION_FAILURE;

    if (Paths==NULL)
    Paths=(double*)malloc(MC_Iterations*BS_Dimension*sizeof(double));
    if (Paths==NULL) return MEMORY_ALLOCATION_FAILURE;

    if (NextPaths==NULL)
    NextPaths=(double*)malloc(MC_Iterations*BS_Dimension*sizeof(double));
    if (NextPaths==NULL) return MEMORY_ALLOCATION_FAILURE;

    if (M==NULL)
    M=(double*)malloc(DimApprox*DimApprox*sizeof(
        double));
    if (M==NULL) return MEMORY_ALLOCATION_FAILURE;

    if (Brownian_Bridge==NULL)
    Brownian_Bridge=(double*)malloc(MC_Iterations*
        BS_Dimension*sizeof(double));
    if (Brownian_Bridge==NULL) return MEMORY_ALLOCATION_FAILURE;
}
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    if (Res==NULL)
    Res=(double*)malloc(DimApprox*sizeof(double));
    if (Res==NULL) return MEMORY_ALLOCATION_FAILURE
        ;

    if (AuxR==NULL)
    AuxR=(double*)malloc(DimApprox*sizeof(double))
        ;
    if (AuxR==NULL) return MEMORY_ALLOCATION_FAILURE;

    if (VBasis==NULL)
    VBasis=(double*)malloc(DimApprox*sizeof(
        double));
    if (VBasis==NULL) return MEMORY_ALLOCATION_FAILURE;

    if (Aux_BS==NULL)
    Aux_BS=(double*)malloc(BS_Dimension*sizeof(
        double));
    if (Aux_BS==NULL)
    return MEMORY_ALLOCATION_FAILURE;

    Chol_Allocation(DimApprox);
    return OK;
}

static void TsRoB_Liberation()
{
    if (FP!=NULL) {
        free(FP);
        FP=NULL;
    }
    if (Paths!=NULL) {
        free(Paths);
        Paths=NULL;
    }
    if (NextPaths!=NULL) {
        free(NextPaths);
        NextPaths=NULL;
    }
}

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    if (M!=NULL) {
        free(M);
        M=NULL;
    }
    if (AuxR!=NULL) {
        free(AuxR);
        AuxR=NULL;
    }
    if (VBasis!=NULL) {
        free(VBasis);
        VBasis=NULL;
    }
    if (Res!=NULL) {
        free(Res);
        Res=NULL;
    }
    if (Aux_BS!=NULL) {
        free(Aux_BS);
        Aux_BS=NULL;
    }
    if (Brownian_Bridge!=NULL) {
        free(Brownian_Bridge);
        Brownian_Bridge=NULL;
    }
    Chol_Liberation();
    return;
}

static double product(double *vect,int AL_Basis_
    Dimension)
{
    int i;
    double aux=0;
    for (i=0;i<AL_Basis_Dimension;i++) aux+=Res[i]*
        Basis(vect,i);
    return aux;
}

static void Regression(NumFunc_1 *p,long AL_Mon
    teCarlo_Iterations, int OP_Exercise_Dates,int AL_
    Basis_Dimension, int BS_Dimension, int Time,int

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    PayOff)
{
    double Aux,AuxOption;
    int i,j;
    long k;

    for (i=0;i<AL_Basis_Dimension;i++){
        AuxR[i]=0;
        for (j=0;j<AL_Basis_Dimension;j++) M[i*AL_Ba
            sis_Dimension+j]=0;
    }

    for(k=0;k<AL_MonteCarlo_Iterations;k++){
        if (PayOff){
            VBasis[0]=(p->Compute) (p->Par,*(Paths+k*BS_
                Dimension));
            for (i=1;i<AL_Basis_Dimension;i++){
                VBasis[i]=Basis(Paths+k*BS_Dimension,i-1);
            }
        } else {
            for (i=0;i<AL_Basis_Dimension;i++){
                VBasis[i]=Basis(Paths+k*BS_Dimension,i);
            }
        }
        for (i=0;i<AL_Basis_Dimension;i++)
            for (j=0;j<AL_Basis_Dimension;j++)
                M[i*AL_Basis_Dimension+j]+=VBasis[i]*VBasis
                    [j];

        AuxOption=(p->Compute) (p->Par,*(NextPaths+k*
            BS_Dimension));
        if (Time==OP_Exercise_Dates-2){
            Aux=AuxOption;
            FP[k]=AuxOption;
        } else {
            Aux=MAX(AuxOption,product(NextPaths+k*BS_Dim
                ension,AL_Basis_Dimension));
            if (AuxOption==Aux){
                FP[k]=Aux;
            }
        }
    }
}

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    }

    for (i=0;i<AL_Basis_Dimension;i++)
        AuxR[i]+=Aux*VBasis[i];
    }
    for (i=0;i<AL_Basis_Dimension;i++){
        AuxR[i]/=(double)AL_MonteCarlo_Iterations;
        for (j=0;j<AL_Basis_Dimension;j++){
            M[i*AL_Basis_Dimension+j]/=(double)AL_MonteC
            arlo_Iterations;
        }
    }
    Cholesky(M,AL_Basis_Dimension);
    Resolution(AuxR,Res,M,AL_Basis_Dimension);
}

/*Canonical Basis for Regression*/
static double CanonicalD1(double *x, int ind)
{
    double aux;
    int i;

    aux=1.;
    for (i=0;i<ind;i++)
        aux*=(*x);
    return aux;
}

static void Init_BrownianBridge(int mc_or_qmc,
    int generator,long MC_Iterations,int dim,double t)
{
    int i;
    long j;
    double squareroott;

    squareroott=sqrt(t);

    for (j=0;j<MC_Iterations;j++)
        for (i=0;i<dim;i++)
            Brownian_Bridge[j*dim+i]=squareroott*Gaussia
            ns[mc_or_qmc](1, CREATE, 0, generator);

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}
static void Compute_Brownian_Bridge(int mc_or_q
    mc,int generator,double *Brownian_Bridge, double
    Time, double Step,
        int BS_Dimension,long
    MonteCarlo_Iterations)
{
    double aux1,aux2,*ad,*admax;

    aux1=Time/(Time+Step);
    aux2=sqrt(aux1*Step);
    ad=Brownian_Bridge;
    admax=Brownian_Bridge+BS_Dimension*MonteCarlo_
        Iterations;

    for (ad=Brownian_Bridge;ad<admax;ad++)
        *ad=aux1*(*ad)+aux2*Gaussians[mc_or_qmc](1, CR
            EATE, 0, generator);
}

static void Backward_Path(double *Paths, double *
    Brownian_Bridge,
        double *BS_Spot,double Time,
        long MonteCarlo_Iterations,
        int BS_Dimension,double *Sigma)
{
    int j,k;
    long n,auxad;
    double aux;

    auxad=0;
    for (n=0;n<MonteCarlo_Iterations;n++){
        for (j=0;j<BS_Dimension;j++){
            aux=0.;
            for (k=0;k<=j;k++)
                aux+=Sigma[j*BS_Dimension+k]*Brownian_Bridg
                    e[auxad+k];
            aux-=Time*Aux_BS[j];
            Paths[auxad+j]=BS_Spot[j]*exp(aux);
        }
    }
}

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    }
    auxad+=BS_Dimension;
}
}

static void TsRoB(double *AL_Price,long AL_MonteC
    arlo_Iterations,NumFunc_1 *p,int AL_Basis_Dimensi
    on,int AL_ShuttingDown,int mc_or_qmc,int genera
    tor,int OP_Exercise_Dates,double *BS_Spot,double
    BS_Maturity,double BS_Interest_Rate,double *BS_Div
    idend_Rate,double *BS_Volatility)
{
    double DiscountStep,Step,Aux,AuxOption,AL_FPri
        ce,AL_BPrice;
    long i;
    int j,k,PayOff,BS_Dimension=1;
    PayOff=0;
    /*Initialization of the regression basis*/
    Basis= CanonicalD1;

    /*Memory Allocation*/
    TsRoB_Allocation(AL_MonteCarlo_Iterations,AL_Ba
        sis_Dimension,BS_Dimension);

    for(j=0;j<AL_Basis_Dimension;j++)
        Res[j]=0;
    AL_BPrice=0.;
    AL_FPrice=0.;

    /*Black-Sholes initalization parameters*/
    Aux_BS[0]=0.5*SQR(BS_Volatility[0])-BS_Interes
        t_Rate+BS_Dividend_Rate[0];
    Step=BS_Maturity/(double)(OP_Exercise_Dates-1);
    DiscountStep=exp(-BS_Interest_Rate*Step);

    /*Initialization of brownian bridge at maturity
    */
    Init_BrownianBridge(mc_or_qmc,generator,AL_Mon
        teCarlo_Iterations,BS_Dimension,BS_Maturity);

    /*Initialization of Black-Sholes Paths at matu

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    rity*/
Backward_Path(NextPaths,Brownian_Bridge,BS_Spot
    ,BS_Maturity,AL_MonteCarlo_Iterations,BS_Dimensi
    on,BS_Volatility);

/*Backward dynamical programming(backward and
    forward are both computed*/
for (k=OP_Exercise_Dates-2;k>=1;k--){
    Compute_Brownian_Bridge(mc_or_qmc,generator,
        Brownian_Bridge,k*Step,Step,BS_Dimension,AL_Mon
        teCarlo_Iterations);
Backward_Path(Paths,Brownian_Bridge,BS_Spot,(
    double)k*Step,AL_MonteCarlo_Iterations,BS_Dimension,
    BS_Volatility);

    Regression(p,AL_MonteCarlo_Iterations,OP_Exe
        rcise_Dates,
        AL_Basis_Dimension,BS_Dimension,k,Pay
        Off);
for (i=0;i<AL_MonteCarlo_Iterations;i++){
    FP[i]*=DiscountStep;
}

for (j=0;j<AL_Basis_Dimension;j++){
    Res[j]*=DiscountStep;
}

for (i=0;i<AL_MonteCarlo_Iterations;i++){
    for (j=0;j<BS_Dimension;j++){
        NextPaths[i*BS_Dimension+j]=Paths[i*BS_Dim
            ension+j];
    }
}

for (i=0;i<AL_MonteCarlo_Iterations;i++){
    AuxOption=(p->Compute) (p->Par,*(NextPaths+i*
        BS_Dimension));
    Aux=MAX(AuxOption,product(NextPaths+i*BS_Dimen
        sion,AL_Basis_Dimension));
    if (AuxOption==Aux){

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    FP[i]=AuxOption;
}
AL_BPrice+=Aux;
FP[i]*=DiscountStep;
}

AuxOption=(p->Compute)(p->Par,*BS_Spot);

/*Backward Price*/
AL_BPrice*=DiscountStep/(double)AL_MonteCarlo_
    Iterations;
AL_BPrice=MAX(AuxOption,AL_BPrice);

Aux=0;
for (i=0;i<AL_MonteCarlo_Iterations;i++){
    Aux+=FP[i];
}
Aux*=DiscountStep/(double)AL_MonteCarlo_Itera
    tions;

/* Forward Price */
AL_FPrice=MAX(AuxOption,Aux);

/*Price = Mean of Forward and Backward Price*/
*AL_Price=0.5*(AL_FPrice+AL_BPrice);

/*Memory Disallocation*/
if (AL_ShuttingDown){
    TsRoB_Liberation();
}
}

static int MCTsitsiklisVanRoy(double s, NumFunc_1
    *p, double t, double r, double dividend,
    double sig, long N, int generator, double inc,int dim
    approx, int exercise_date_number,double *ptprice,
    double *ptdelta)
{

    double p1,p2,p3;
    int simulation_dim= 1,fermeture=1,init_mc,

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    mc_or_qmc;
double s_vector[1];
double s_vector_plus[1];
double divid[1];
double sigma[1];

/*Initialisation*/
s_vector[0]=s;
s_vector_plus[0]=s*(1.+inc);
divid[0]=dividend;
sigma[0]=sig;

/*MC sampling*/
init_mc= InitGenerator(generator,simulation_dim
,N);

/* Test after initialization for the generator
*/
if(init_mc == OK)
{   mc_or_qmc= Rand_Or_Quasi(generator);

/*Geske-Johnson Formulae*/
if (exercise_date_number==0) {
    TsRoB(&p1,N,p,dimapprox,fermeture,mc_or_qmc,
generator,2,s_vector,t,r,divid,sigma);
    TsRoB(&p2,N,p,dimapprox,fermeture,mc_or_qmc,
generator,3,s_vector,t,r,divid,sigma);
    TsRoB(&p3,N,p,dimapprox,fermeture,mc_or_qmc,
generator,4,s_vector,t,r,divid,sigma);
    *ptprice=p3+7./2.*(p3-p2)-(p2-p1)/2.;
} else {
    TsRoB(ptprice,N,p,dimapprox,fermeture,mc_or_
qmc,generator,exercise_date_number,s_vector,t,r,
divid,sigma);
}

/*Delta*/
if (exercise_date_number==0)
{
    TsRoB(&p1,N,p,dimapprox,fermeture,mc_or_q
mc,generator,2,s_vector_plus,t,r,divid,sigma);

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    TsRoB(&p2,N,p,dimapprox,fermeture,mc_or_q
    mc,generator,3,s_vector_plus,t,r,divid,sigma);
    TsRoB(&p3,N,p,dimapprox,fermeture,mc_or_q
    mc,generator,4,s_vector_plus,t,r,divid,sigma);
    *ptdelta=((p3+7./2.*(p3-p2)-(p2-p1)/2.)*pt
    price)/(s*inc);
}
else
{
    TsRoB(&p1,N,p,dimapprox,fermeture,mc_or_q
    mc,generator,exercice_date_number,s_vector_plus,t,
    r,divid,sigma);
    *ptdelta=(p1-*ptprice)/(s*inc);
}

}

return init_mc;
}

int CALC(MC_TsitsiklisVanRoy)(void *Opt, void *
    Mod, PricingMethod *Met)
{
    TYPEOPT* ptOpt=(TYPEOPT*)Opt;
    TYPEMOD* ptMod=(TYPEMOD*)Mod;
    double r,divid;

    r=log(1.+ptMod->R.Val.V_DOUBLE/100.);
    divid=log(1.+ptMod->Divid.Val.V_DOUBLE/100.);

    return MCTsitsiklisVanRoy(ptMod->S0.Val.V_PDOU
    BLE,
        ptOpt->PayOff.Val.V_NUMFUNC_
    1,
        ptOpt->Maturity.Val.V_DATE-
    ptMod->T.Val.V_DATE,
        r,
        divid,
        ptMod->Sigma.Val.V_PDOUBLE,
        Met->Par[0].Val.V_LONG,
        Met->Par[1].Val.V_INT,

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        Met->Par[2].Val.V_PDOUBLE,
        Met->Par[3].Val.V_INT,
        Met->Par[4].Val.V_INT,
        &(Met->Res[0].Val.V_DOUBLE),
        &(Met->Res[1].Val.V_DOUBLE))
    ;
}

int CHK_OPT(MC_TsitsiklisVanRoy)(void *Opt, void
    *Mod)
{
    Option* ptOpt=(Option*)Opt;
    TYPEOPT* opt=(TYPEOPT*)(ptOpt->TypeOpt);

    if ((opt->EuOrAm).Val.V_BOOL==AMER)
        return OK;
    else
        return WRONG;
}

static int MET(Init)(PricingMethod *Met)
{
    static int first=1;
    int type_generator;

    type_generator= Met->Par[1].Val.V_INT;

    if (first)
    {
        Met->Par[0].Val.V_LONG=50000;
        Met->Par[1].Val.V_INT=0;
        Met->Par[2].Val.V_PDOUBLE=0.1;
        Met->Par[3].Val.V_INT=8;
        Met->Par[4].Val.V_INT=20;
        first=0;
    }
    return OK;
}

PricingMethod MET(MC_TsitsiklisVanRoy)=
{

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"MC_TsitsiklisVanRoy",
{{"N iterations",LONG,100,ALLOW},
 {"RandomGenerator",GENER,100,ALLOW},
 {"Delta Increment Rel",PDOUBLE,100,ALLOW},
 {"Dimension Approximation",INT,100,ALLOW},
 {"Number of Exercise Dates (0->Geske Johnson
  Formulae",INT,100,ALLOW},
 {" ",END,0,FORBID}}},
CALC(MC_TsitsiklisVanRoy),
{{"Price",DOUBLE,100,FORBID},
 {"Delta",DOUBLE,100,FORBID} ,
 {" ",END,0,FORBID}}},
CHK_OPT(MC_TsitsiklisVanRoy),
CHK_mc,
MET(Init)
};

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## References