

[Help](#)

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#include "bs1d_std.h"

static double *Mesh=NULL, *Path=NULL, *Price=NULL, *VectInvMeshDensity=NULL;
static double *Aux_BS_TD_1=NULL, *Aux_BS_TD_2=NULL, *InvSigma=NULL;
static double Norm_BS_TD, DetInvSigma;
static double *AuxBS=NULL, *Sigma=NULL, *Aux_Stock=NULL;

static int BrGl_Allocation(long AL_Mesh_Size,
                           int OP_Exercise_Dates, int
                           BS_Dimension)
{
    int dummy;

    if (Mesh==NULL)
        Mesh=(double*)malloc(AL_Mesh_Size*OP_Exercise_
                               Dates*BS_Dimension*sizeof(double));
    if (Mesh==NULL)
        return MEMORY_ALLOCATION_FAILURE;

    if (Price==NULL)
        Price=(double*)malloc(AL_Mesh_Size*OP_Exercise_
                               Dates*sizeof(double));
    if (Price==NULL)
        return MEMORY_ALLOCATION_FAILURE;

    if (Path==NULL)
        Path=(double*)malloc(OP_Exercise_Dates*BS_Dim
                               ension*sizeof(double));

    if (Path==NULL)
        return MEMORY_ALLOCATION_FAILURE;

    if (VectInvMeshDensity==NULL)
        VectInvMeshDensity=(double*)malloc(AL_Mesh_Siz
                                              e*sizeof(double));

    if (VectInvMeshDensity==NULL)
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return MEMORY_ALLOCATION_FAILURE;

if (Aux_BS_TD_1==NULL)
Aux_BS_TD_1=(double*)malloc(BS_Dimension*sizeof
    f(double));
if (Aux_BS_TD_1==NULL)
return MEMORY_ALLOCATION_FAILURE;

if (Aux_BS_TD_2==NULL)
Aux_BS_TD_2=(double*)malloc(BS_Dimension*sizeof
    f(double));
if (Aux_BS_TD_2==NULL)
return MEMORY_ALLOCATION_FAILURE;

if (InvSigma==NULL)
InvSigma=(double*)malloc(BS_Dimension*BS_Dimen
    sion*sizeof(double));
if (InvSigma==NULL)
return MEMORY_ALLOCATION_FAILURE;

if (Sigma==NULL)
Sigma=(double*)malloc(BS_Dimension*BS_Dimensi
    on*sizeof(double));
if (Sigma==NULL)
return MEMORY_ALLOCATION_FAILURE;

if (AuxBS==NULL)
AuxBS=(double*)malloc(BS_Dimension*sizeof(
    double));
if (AuxBS==NULL)
return MEMORY_ALLOCATION_FAILURE;

if (Aux_Stock==NULL)
Aux_Stock=(double*)malloc(BS_Dimension*sizeof(
    double));
if (Aux_Stock==NULL)
return MEMORY_ALLOCATION_FAILURE;

dummy=Chol_Allocation(BS_Dimension);

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    return OK;
}

static void Brod_Liberation()
{
    if (Mesh!=NULL) {
        free(Mesh);
        Mesh=NULL;
    }

    if (Price!=NULL) {
        free(Price);
        Price=NULL;
    }

    if (Path!=NULL) {
        free(Path);
        Path=NULL;
    }

    if (VectInvMeshDensity!=NULL) {
        free(VectInvMeshDensity);
        VectInvMeshDensity=NULL;
    }

    if (Aux_BS_TD_1!=NULL) {
        free(Aux_BS_TD_1);
        Aux_BS_TD_1=NULL;
    }

    if (Aux_BS_TD_2!=NULL) {
        free(Aux_BS_TD_2);
        Aux_BS_TD_2=NULL;
    }

    if (InvSigma!=NULL) {
        free(InvSigma);
        InvSigma=NULL;
    }

    if (Aux_Stock!=NULL) {
        free(Aux_Stock);
    }
}
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    Aux_Stock=NULL;
}

    if (AuxBS!=NULL) {
        free(AuxBS);
        AuxBS=NULL;
    }

    if (Sigma!=NULL) {
        free(Sigma);
        Sigma=NULL;
    }
    Chol_Liberation();
}

static double Discount(double Time, double BS_
    Interest_Rate)
{
    return exp(-BS_Interest_Rate*Time);
}

static void BS_Transition_Allocation(int BS_Dimen
    sion, double Step)
{
    int i,j;

    for (i=0;i<BS_Dimension;i++)
    for (j=0;j<BS_Dimension;j++)
        InvSigma[i*BS_Dimension+j]=Sigma[i*BS_Dimen
            sion+j];

    InverseCholesky(InvSigma,BS_Dimension);

    /* determinant of InvSigma */
    DetInvSigma=1;
    for (i=0;i<BS_Dimension;i++)
        DetInvSigma*=InvSigma[i*BS_Dimension+i];

    Norm_BS_TD=exp(-BS_Dimension*0.5*log(2.*PI*Ste
        p));

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}

/*Black-Sholes Conditional Density function know
   ing Z*/
static double BS_TD(double *X, double *Z, int BS_
    Dimension, double Step)
{
    int i,j;
    double aux1,aux2;

    for (i=0;i<BS_Dimension;i++){
        Aux_BS_TD_1[i]=log(Z[i]/X[i])+Step*AuxBS[i];
    }
    aux1=Z[0];
    for (i=1;i<BS_Dimension;i++){
        aux1*=Z[i];
    }
    if (aux1==0){
        return -1;
    }
    else {
        for (i=0;i<BS_Dimension;i++){
            Aux_BS_TD_2[i]=0;
            for (j=0;j<=i;j++){
                Aux_BS_TD_2[i]+=InvSigma[i*BS_Dimension+j]*
                    Aux_BS_TD_1[j];
            }
        }
        aux2=0;
        for (i=0;i<BS_Dimension;i++){
            aux2+=Aux_BS_TD_2[i]*Aux_BS_TD_2[i];
        }
        aux2=exp(-aux2/(2.*Step));
        return Norm_BS_TD*DetInvSigma*aux2/aux1;
    }
}

static double MeshDensity(int Time, double *Stock
    , int OP_Exercise_Dates, int AL_Mesh_Size,int
    BS_Dimension, double *BS_Spot, double Step)
{

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    long k;
    double aux=0;

    if (Time>1){
    for (k=0;k<AL_Mesh_Size;k++)
        aux+=BS_TD(Mesh+k*OP_Exercise_Dates*BS_Dimen
            sion+(Time-1)*BS_Dimension,Stock,BS_Dimension,Ste
            p);
    return aux/(double)AL_Mesh_Size;
    } else {
    return BS_TD(BS_Spot,Stock,BS_Dimension,Step);
    }
}

static double Weight(int Time, double *iStock,
    double *jStock, int j, int BS_Dimension,
    double Step)
{
    if (Time>0){
    return BS_TD(iStock,jStock,BS_Dimension,Step)*
        VectInvMeshDensity[j];
    } else {
    return 1.;
    }
}

/*Black-Sholes Step*/
static void BS_Forward_Step(int mc_or_qmc,int gen
    erator,double *Stock, double *Initial_Stock, int
    BS_Dimension,double Step,double Sqrt_Step)
{
    int j,k;
    double Aux;

    for (j=0;j<BS_Dimension;j++){
    Aux_Stock[j]=Sqrt_Step*Gaussians[mc_or_qmc](1,
        CREATE, 0, generator);
    }
    for (j=0;j<BS_Dimension;j++){
    Aux=0.;

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    for (k=0;k<=j;k++){
        Aux+=Sigma[j*BS_Dimension+k]*Aux_Stock[k];
    }
    Aux-=Step*AuxBS[j];
    Stock[j]=Initial_Stock[j]*exp(Aux);
}
}

static void InitMesh(int mc_or_qmc,int generator,
    int AL_Mesh_Size, int BS_Dimension, double *BS_Spot,
    ,int OP_Exercise_Dates, double Step, double Sqrt
    _Step)
{
    int j,k, aux;

    for (k=0;k<AL_Mesh_Size;k++){
        BS_Forward_Step(mc_or_qmc,generator,Mesh+k*OP_
            Exercise_Dates*BS_Dimension+BS_Dimension,BS_Spot,
            BS_Dimension,Step,Sqrt_Step);
    }
    for (j=2;j<OP_Exercise_Dates;j++){
        for (k=0;k<AL_Mesh_Size;k++){

            aux=(int) (AL_Mesh_Size*Uniform(generator))
            ;

            BS_Forward_Step(mc_or_qmc,generator,Mesh+k*
                OP_Exercise_Dates*BS_Dimension+j*BS_Dimension,Mes
                h+aux*OP_Exercise_Dates*BS_Dimension+(j-1)*BS_Dim
                ension,BS_Dimension,Step,Sqrt_Step);
        }
    }
}

static void BrGl(double *AL_Price,
    long AL_MonteCarlo_Iterations,
    NumFunc_1 *p, int AL_Mesh_Size,
    int AL_ShuttingDown,
    int mc_or_qmc,int generator,
    int OP_Exercise_Dates,

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        double *BS_Spot,
        double BS_Maturity,
        double BS_Interest_Rate,
        double *BS_Dividend_Rate,
        double *BS_Volatility,
        int gj_flag)
{
    double aux,Step,Sqrt_Step,DiscountStep;
    long i,j,k;
    int l;
    double AL_BPrice,AL_FPrice;
    int BS_Dimension=1;

    AL_BPrice=0.;
    AL_FPrice=0.;
    Step=BS_Maturity/(double)(OP_Exercise_Dates-1);
    Sqrt_Step=sqrt(Step);
    DiscountStep=exp(-BS_Interest_Rate*Step);

    /*Memory Allocation*/
    BrGl_Allocation(AL_Mesh_Size,OP_Exercise_Dates,
        BS_Dimension);

    /*Black-Sholes initialization parameters*/
    Sigma[0]=BS_Volatility[0];
    BS_Transition_Allocation(BS_Dimension,Step);
    AuxBS[0]=0.5*SQR(BS_Volatility[0])-BS_Interest_
        Rate+BS_Dividend_Rate[0];

    /*Initialization of the mesh*/
    InitMesh(mc_or_qmc,generator,AL_Mesh_Size,BS_
        Dimension,BS_Spot,OP_Exercise_Dates,Step,Sqrt_Ste
        p);

    for (i=0;i<AL_Mesh_Size;i++)
    Price[i*OP_Exercise_Dates+OP_Exercise_Dates-1]
        =0.;

    /* Dynamical programing: Backward Price */

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for (j=OP_Exercise_Dates-2;j>=1;j--){
  for (i=0;i<AL_Mesh_Size;i++){
    VectInvMeshDensity[i]=1./MeshDensity(j+1,Mes
h+i*OP_Exercise_Dates*BS_Dimension+(j+1)*BS_Dimen
sion,OP_Exercise_Dates,AL_Mesh_Size,BS_Dimension,
BS_Spot,Step);
  }
  for (i=0;i<AL_Mesh_Size;i++){
    aux=0;
    for (k=0;k<AL_Mesh_Size;k++){

      /*Payoff control variate*/
      aux+=(Price[k*OP_Exercise_Dates+j+1]+
        (p->Compute) (p->Par,*(Mesh+k*OP_Exerc
ise_Dates*BS_Dimension+(j+1)*BS_Dimension)))*Weig
ht(j,Mesh+i*OP_Exercise_Dates*BS_Dimension+j*BS_
Dimension,Mesh+k*OP_Exercise_Dates*BS_Dimension+(
j+1)*BS_Dimension,k,BS_Dimension,Step);
    }
    aux*=DiscountStep/(double)AL_Mesh_Size;
    aux-=(p->Compute) (p->Par,*(Mesh+i*OP_Exercis
e_Dates*BS_Dimension+j*BS_Dimension));
    Price[i*OP_Exercise_Dates+j]=MAX(0,aux);
  }
}

aux=0;
for (i=0;i<AL_Mesh_Size;i++){
  aux+=Price[i*OP_Exercise_Dates+1]+(p->Compute)
    (p->Par,*(Mesh+i*OP_Exercise_Dates*BS_Dimension
+BS_Dimension));
}

/*Backward Price*/
if(!gj_flag)
  AL_BPrice=MAX((p->Compute) (p->Par,*(BS_Spot)),
    DiscountStep*aux/(double)AL_Mesh_Size);
else
  AL_BPrice=DiscountStep*aux/(double)AL_Mesh_Siz
e;

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/* Forward Price */
AL_FPrice=0;
for(i=0;i<AL_MonteCarlo_Iterations;i++){

for (l=0;l<BS_Dimension;l++){
    Path[l]=BS_Spot[l];
}

j=0;
do {
    aux=0;
    for (k=0;k<AL_Mesh_Size;k++){
        aux+=(Price[k*OP_Exercise_Dates+j+1]+(p->
        Compute)(p->Par,*(Mesh+k*OP_Exercise_Dates*BS_Dimen
        sion+(j+1)*BS_Dimension)))*Weight(j,Path+j*BS_Dim
        ension,Mesh+k*OP_Exercise_Dates*BS_Dimension+(j+1
        )*BS_Dimension,k,BS_Dimension,Step);
    }
    aux*=DiscountStep/(double)AL_Mesh_Size;
    aux-=(p->Compute)(p->Par,*(Path+j*BS_Dimensi
    on));

    j++;
    BS_Forward_Step(mc_or_qmc,generator,Path+j*
    BS_Dimension,Path+(j-1)*BS_Dimension,BS_Dimension,
    Step,Sqrt_Step);
}
while ((0<aux)&&(j<OP_Exercise_Dates-1));
AL_FPrice+=Discount((double)(j)*Step,BS_Inter
    est_Rate)*(p->Compute)(p->Par,*(Path+(j)*BS_Dim
    ension));
}
AL_FPrice/=(double)AL_MonteCarlo_Iterations;

/*Price = Mean of Forward and Backward Price*/
*AL_Price=0.5*(AL_FPrice+AL_BPrice);

/*Memory Disallocation*/
if (AL_ShuttingDown){
    Brod_Liberation();
}

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    }
}

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static int MCBroadieGlassermann(double s,
    NumFunc_1 *p, double t, double r, double dividend,
    double sig, long N, int generator, double inc,int mes
    h_size, int exercise_date_number,double *ptprice,
    double *ptdelta)
{

    double p1,p2,p3;
    int simulation_dim= 1,fermeture=1,init_mc,
        mc_or_qmc;
    double s_vector[1];
    double s_vector_plus[1];
    double divid[1];
    double sigma[1];

    /*Initialisation*/
    s_vector[0]=s;
    s_vector_plus[0]=s*(1.+inc);
    divid[0]=dividend;
    sigma[0]=sig;
    /*MC sampling*/
    init_mc= InitGenerator(generator,simulation_dim
        ,N);

    /* Test after initialization for the generator
    */
    if(init_mc == OK)
        { mc_or_qmc= Rand_Or_Quasi(generator);

    /*Geske-Johnson Formulae*/
    if (exercise_date_number==0) {
        BrGl(&p3,N,p,mesh_size,fermeture,mc_or_qmc,g
            enerator,4,s_vector,t,r,divid,sigma,1);
        BrGl(&p2,N,p,mesh_size,fermeture,mc_or_qmc,g
            enerator,3,s_vector,t,r,divid,sigma,1);
    }
}

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    BrGl(&p1,N,p,mesh_size,fermeture,mc_or_qmc,g
    enerator,2,s_vector,t,r,divid,sigma,1);
    *ptprice=p3+7./2.*(p3-p2)-(p2-p1)/2.;
} else {
    BrGl(ptprice,N,p,mesh_size,fermeture,mc_or_q
    mc,generator,exercice_date_number,s_vector,t,r,div
    id,sigma,0);
}

/*Delta*/
if (exercice_date_number==0) {
    BrGl(&p3,N,p,mesh_size,fermeture,mc_or_qmc,g
    enerator,4,s_vector_plus,t,r, divid,sigma,1);
    BrGl(&p2,N,p,mesh_size,fermeture,mc_or_qmc,g
    enerator,3,s_vector_plus,t,r,divid,sigma,1);
    BrGl(&p1,N,p,mesh_size,fermeture,mc_or_qmc,g
    enerator,2,s_vector_plus,t,r,divid,sigma,1);
    *ptdelta=((p3+7./2.*(p3-p2)-(p2-p1)/2.)*pt
    price)/(s*inc);
} else {
    BrGl(&p1,N,p,mesh_size,fermeture,mc_or_qmc,g
    enerator,exercice_date_number,s_vector_plus,t,r,
    divid,sigma,0);
    *ptdelta=(p1-*ptprice)/(s*inc);
}
}
return init_mc;
}

int CALC(MC_BroadieGlassermann)(void *Opt, void *
    Mod, PricingMethod *Met)
{
    TYPEOPT* ptOpt=(TYPEOPT*)Opt;
    TYPEMOD* ptMod=(TYPEMOD*)Mod;
    double r,divid;

    r=log(1.+ptMod->R.Val.V_DOUBLE/100.);
    divid=log(1.+ptMod->Divid.Val.V_DOUBLE/100.);

    return MCBroadieGlassermann(ptMod->S0.Val.V_PD
    OUBLE,

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        ptOpt->PayOff.Val.V_
NUMFUNC_1,
        ptOpt->Maturity.Val.V_DA
TE-ptMod->T.Val.V_DATE,
        r,
        divid,
        ptMod->Sigma.Val.V_PDOUBL
E,
        Met->Par[0].Val.V_LONG,
        Met->Par[1].Val.V_INT,
        Met->Par[2].Val.V_PDOUBLE,
        Met->Par[3].Val.V_INT,
        Met->Par[4].Val.V_INT,
        &(Met->Res[0].Val.V_
DOUBLE),
        &(Met->Res[1].Val.V_
DOUBLE));
}

int CHK_OPT(MC_BroadieGlassermann)(void *Opt, vo
id *Mod)
{
    Option* ptOpt=(Option*)Opt;
    TYPEOPT* opt=(TYPEOPT*)(ptOpt->TypeOpt);

    if ((opt->EuOrAm).Val.V_BOOL==AMER)
        return OK;
    else
        return WRONG;
}

static int MET(Init)(PricingMethod *Met)
{
    static int first=1;
    int type_generator;

    type_generator= Met->Par[1].Val.V_INT;

    if (first)

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    {
        Met->Par[0].Val.V_LONG=10000;
        Met->Par[1].Val.V_INT=0;
        Met->Par[2].Val.V_PDOUBLE=0.1;
        Met->Par[3].Val.V_INT=200;
        Met->Par[4].Val.V_INT=10;
        first=0;
    }
    return OK;
}

PricingMethod MET(MC_BroadieGlassermann)=
{
    "MC_BroadieGlassermann",
    {"N iterations",LONG,100,ALLOW},
    {"RandomGenerator",GENER,100,ALLOW},
    {"Delta Increment Rel",PDOUBLE,100,ALLOW},
    {"Mesh Size",INT,100,ALLOW},
    {"Number of Exercise Dates (0->Geske Johnson
        Formulae",INT,100,ALLOW},
    {" ",END,0,FORBID}},
    CALC(MC_BroadieGlassermann),
    {"Price",DOUBLE,100,FORBID},
    {"Delta",DOUBLE,100,FORBID} ,
    {" ",END,0,FORBID}},
    CHK_OPT(MC_BroadieGlassermann),
    CHK_mc,
    MET(Init)
};

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References