

[Help](#)

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#include "bs2d_std2d.h"

static int restriction22(int l,double **d,
    double **u,double **f,double **aa,double **bb,int N)
{
    int i,j,nl;
    double **w;

    nl=nn(l);

    w=(double **)calloc(nl+2,sizeof(double *));
    if (w==NULL)
        return MEMORY_ALLOCATION_FAILURE;
    for (i=0;i<nl+2;i++)
    {
        w[i]=(double *)calloc(nl+2,sizeof(double));
        if (w[i]==NULL)
            return MEMORY_ALLOCATION_FAILURE;
    }

    for (i=1;i<nl+1;i++)
        for (j=1;j<nl+1;j++)
            w[i][j]=u[i][j]*aa[i*N/(nl+1)][j*N/(nl+1)]
                +(u[i+1][j]+u[i-1][j]+u[i][j+1]+u[i][j-1])*bb[
                    i*N/(nl+1)][j*N/(nl+1)]-f[i][j];

    for (i=2;i<nl;i=i+2)
        for (j=2;j<nl;j=j+2)
            d[i/2][j/2]=(((w[i-1][j-1]+w[i+1][j-1]+w
                [i-1][j+1]+w[i+1][j+1])/2.0+w[i][j-1]+w[i+1][j]+
                w[i-1][j]+w[i][j+1])/2.0+w[i][j])/4.0;

    for (i=0;i<nl+2;i++)
        free(w[i]);
    free(w);

    return OK;
}
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static int substract_prolongation2(int l,double *
    *u,double **v)
{
    int nl,nl1,i,j;
    double **w;

    nl=nn(l);
    nl1=nn(l-1);

    w=(double **)calloc(nl+2,sizeof(double *));
    if (w==NULL)
        return MEMORY_ALLOCATION_FAILURE;
    for (i=0;i<nl+2;i++)
    {
        w[i]=(double *)calloc(nl+2,sizeof(double));
        if (w[i]==NULL)
            return MEMORY_ALLOCATION_FAILURE;
    }

    for (i=1;i<nl+1;i=i+2)
        {w[i][0]=w[0][i]=w[nl+1][i]=w[i][nl+1]=0.0;
        }

    for (i=0;i<nl1+2;i++)
        for (j=0;j<nl1+2;j++)
            w[2*i][2*j]=v[i][j];

    for (i=1;i<nl+1;i=i+2)
        for (j=2;j<nl;j=j+2)
            w[i][j]=(w[i-1][j]+w[i+1][j])/2.0;

    for (i=1;i<nl+1;i++)
        for (j=1;j<nl+1;j=j+2)
            w[i][j]=(w[i][j-1]+w[i][j+1])/2.0;

    for (i=1;i<nl+1;i++)
        for (j=1;j<nl+1;j++)
            u[i][j]=u[i][j]-w[i][j];

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    for (i=0;i<nl+2;i++)
        free(w[i]);
    free(w);

    return OK;
}

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static int MGM22(int l,double **u,double **f,
    double **aa,double **bb,int N)
{
    int i,j,nl,ii,nl1,dummy;
    double **d,**v;

    nl=nn(l);
    nl1=nn(l-1);

    d=(double **)calloc(nl1+2,sizeof(double *));
    if (d==NULL)
        return MEMORY_ALLOCATION_FAILURE;
    for (i=0;i<nl1+2;i++)
    {
        d[i]=(double *)calloc(nl1+2,sizeof(double))
        ;
        if (d[i]==NULL)
            return MEMORY_ALLOCATION_FAILURE;
    }

    v=(double **)calloc(nl1+2,sizeof(double *));
    if (v==NULL)
        return MEMORY_ALLOCATION_FAILURE;
    for (i=0;i<nl1+2;i++)
    {
        v[i]=(double *)calloc(nl1+2,sizeof(double))
        ;
        if (v[i]==NULL)
            return MEMORY_ALLOCATION_FAILURE;
    }

    if (l==0) u[1][1]=f[1][1]/(aa[N/2][N/2]);

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else
{
/* 2 iterations of Gauss-Seidel*/
for (ii=1;ii<3;ii++)
for (i=1;i<nl+1;i++)
for (j=1;j<nl+1;j++)
u[i][j]=((-u[i+1][j]-u[i-1][j]-u[
i][j+1]-u[i][j-1])*bb[i*N/(nl+1)][j*N/(nl+1)]+f[
i][j])/aa[i*N/(nl+1)][j*N/(nl+1)];

dummy=restriction22(l,d,u,f,aa,bb,N);

for (i=0;i<=nl+1;i++)
for (j=0;j<=nl+1;j++)
v[i][j]=0.0;

dummy=MGM22(l-1,v,d,aa,bb,N);

dummy=substract_prolongation2(l,u,v);

/* 2 iterations of Gauss-Seidel*/
for (ii=1;ii<3;ii++)
for (i=1;i<nl+1;i++)
for (j=1;j<nl+1;j++)
u[i][j]=((-u[i+1][j]-u[i-1][j]-u[
i][j+1]-u[i][j-1])*bb[i*N/(nl+1)][j*N/(nl+1)]+f[
i][j])/aa[i*N/(nl+1)][j*N/(nl+1)];
}

for (i=0;i<nl+2;i++)
free(v[i]);
free(v);

for (i=0;i<nl+2;i++)
free(d[i]);
free(d);

return OK;
}

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static int mult_amer2(double s1,double s2,
    NumFunc_2 *p,double t,double r,double divid1,double div
    id2,double sigma1,double sigma2,double rho,int l,
    int M,double epsilon, double *ptprice,double *ptde
    lta1,double *ptdelta2)
{
double h,x1,x2,k,limit,aa,bb,gg1,gg0,sigma11,
    sigma12,sigma21,sigma22,m1,m2,trend1,trend2;
double **P,**Obst,**A,**B,**G,**R;
int Index,TimeIndex,i,j,jj,N;
int **pp;

/*Memory Allocation*/
N=nn(l)+1;
P=(double **)calloc(N+1,sizeof(double *));
if (P==NULL)
return MEMORY_ALLOCATION_FAILURE;
for (i=0;i<N+1;i++)
{
P[i]=(double *)calloc(N+1,sizeof(double));
if (P[i]==NULL)
return MEMORY_ALLOCATION_FAILURE;
}

Obst=(double **)calloc(N+1,sizeof(double *));
if (Obst==NULL)
return MEMORY_ALLOCATION_FAILURE;
for (i=0;i<N+1;i++)
{
Obst[i]=(double *)calloc(N+1,sizeof(double)
);
if (Obst[i]==NULL)
return MEMORY_ALLOCATION_FAILURE;
}

pp=(int **)calloc(N+1,sizeof(int *));
if (pp==NULL)
return MEMORY_ALLOCATION_FAILURE;
for (i=0;i<N+1;i++)
{
pp[i]=(int *)calloc(N+1,sizeof(int));

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    if (pp[i]==NULL)
        return MEMORY_ALLOCATION_FAILURE;
}

R=(double **)calloc(N+1,sizeof(double *));
if (R==NULL)
    return MEMORY_ALLOCATION_FAILURE;
for (i=0;i<N+1;i++)
{
    R[i]=(double *)calloc(N+1,sizeof(double));
    if (R[i]==NULL)
        return MEMORY_ALLOCATION_FAILURE;
}

G=(double **)calloc(N+1,sizeof(double *));
if (G==NULL)
    return MEMORY_ALLOCATION_FAILURE;
for (i=0;i<N+1;i++)
{
    G[i]=(double *)calloc(N+1,sizeof(double));
    if (G[i]==NULL)
        return MEMORY_ALLOCATION_FAILURE;
}

A=(double **)calloc(N+1,sizeof(double *));
if (A==NULL)
    return MEMORY_ALLOCATION_FAILURE;
for (i=0;i<N+1;i++)
{
    A[i]=(double *)calloc(N+1,sizeof(double));
    if (A[i]==NULL)
        return MEMORY_ALLOCATION_FAILURE;
}

B=(double **)calloc(N+1,sizeof(double *));
if (B==NULL)
    return MEMORY_ALLOCATION_FAILURE;
for (i=0;i<N+1;i++)
{
    B[i]=(double *)calloc(N+1,sizeof(double));
    if (B[i]==NULL)
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    return MEMORY_ALLOCATION_FAILURE;
}

/*Covariance Matrix*/
sigma11=sigma1;
sigma12=0.0;
sigma21=rho*sigma2;
sigma22=sigma2*sqrt(1.0-SQR(rho));
m1=(r-divid1)-SQR(sigma11)/2.0;
m2=(r-divid2)-(SQR(sigma21)+SQR(sigma22))/2.0;

/*Space Localisation*/
limit=sqrt(t)*sqrt(log(1/PRECISION));
h=2.*limit/(double)N;

/*Time Step*/
k=t/(double)M;

/*Terminal Values*/
x1=log(s1);
x2=log(s2);
trend1=exp(x1+m1*t);
trend2=exp(x2+m2*t);

for (j=1;j<N;j++)
    for (i=1;i<N;i++)
        P[i][j]=(p->Compute)(p->Par,trend1*exp(
            sigma11*(-limit+h*(double)j)),trend2*exp(sigma21*
            (-limit+h*(double)j)+sigma22*(limit-h*(double)i)
        ));

/*Homegenous Dirichlet Conditions*/
for(i=0;i<=N;i++)
{
    P[i][0]=0.;
    P[i][N]=0.;
    P[0][i]=0.;
    P[N][i]=0.;
}

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aa=1.+2.*k/h/h+r*k;
bb=-1.*k/2./h/h;

/*Finite Difference Cycle*/
for (TimeIndex=1;TimeIndex<M+1;TimeIndex++)
{
    trend1=exp(x1+m1*(t-TimeIndex*k));
    trend2=exp(x2+m2*(t-TimeIndex*k));

    for (j=1;j<N;j++)
        for (i=1;i<N;i++)
            Obst[i][j]=(p->Compute)(p->Par,trend1
*exp(sigma11*(-limit+h*(double)j)),trend2*exp(sigma21*(-limit+h*(double)j)+sigma22*(limit-h*(double)i)));

/*Init Control*/
for (i=0;i<=N;i++)
    for (j=0;j<=N;j++)
    {
        pp[i][j]=0;
        R[i][j]=-P[i][j];
    }

/*Howard Cycle*/
for (jj=0;jj<2;jj++)
{
    for (i=1;i<N;i++)
        for (j=1;j<N;j++)
        {
            gg0=P[i][j]*aa+(P[i+1][j]+P[i-1][j]+P[i][j+1]+P[i][j-1])*bb-P[i][j];
            gg1=P[i][j]-Obst[i][j];
            if (gg0<gg1) pp[i][j]=0;else pp[i][j]=1;
        }

    for (i=1;i<N;i++)
        for (j=1;j<N;j++)
        {
            if (pp[i][j]==0)

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        {
            G[i][j]=-R[i][j];A[i][j]=aa;B[
i][j]=bb;
        }
        else
        {
            G[i][j]=Obst[i][j];A[i][j]=1;B[
i][j]=0;
        }
    }

    /*Solve the system*/
    MGM22(1,P,G,A,B,N);
}
/*End Howard Cycle*/
}
/*End Finite Difference Cycle*/

Index=(int)((double)N/2.0);

/*Price*/
*ptprice=P[Index][Index];

/*Deltas*/
*ptdelta2=(P[Index-1][Index]-P[Index+1][Index]
)/(2.*s2*h*sigma22);
*ptdelta1=((P[Index][Index+1]-P[Index][Index-1]
))/(2.*s1*h)-sigma21*(*ptdelta2)/sigma11;

/*Memory desallocation*/
for (i=0;i<N+1;i++)
    free(P[i]);
free(P);

for (i=0;i<N+1;i++)
    free(Obst[i]);
free(Obst);

for (i=0;i<N+1;i++)
    free(A[i]);

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    free(A);

    for (i=0;i<N+1;i++)
        free(B[i]);
    free(B);

    for (i=0;i<N+1;i++)
        free(R[i]);
    free(R);

    for (i=0;i<N+1;i++)
        free(G[i]);
    free(G);

    for (i=0;i<N+1;i++)
        free(pp[i]);
    free(pp);

    return OK;
}

int CALC(FD_FMGH)(void *Opt,void *Mod,Pricing
    Method *Met)
{
    TYPEOPT* ptOpt=(TYPEOPT*)Opt;
    TYPEMOD* ptMod=(TYPEMOD*)Mod;
    double r,divid1,divid2;

    r=log(1.+ptMod->R.Val.V_DOUBLE/100.);
    divid1=log(1.+ptMod->Divid1.Val.V_DOUBLE/100.
    );
    divid2=log(1.+ptMod->Divid2.Val.V_DOUBLE/100.
    );

    return mult_amer2(ptMod->S01.Val.V_PDOUBLE,pt
    Mod->S02.Val.V_PDOUBLE,ptOpt->PayOff.Val.V_
    NUMFUNC_2,
        ptOpt->Maturity.Val.V_DATE-ptMod->T.Val.
    V_DATE,r,divid1,divid2,
        ptMod->Sigma1.Val.V_PDOUBLE,ptMod->Sigma2
    .Val.V_PDOUBLE,ptMod->Rho.Val.V_RGDOUBLE,

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        Met->Par[0].Val.V_INT,Met->Par[1].Val.V_
INT,Met->Par[2].Val.V_RGDOUBLE,
        &(Met->Res[0].Val.V_DOUBLE),&(Met->Res[1]
.Val.V_DOUBLE),&(Met->Res[2].Val.V_DOUBLE) );
    }

int CHK_OPT(FD_FMGH)(void *Opt, void *Mod)
{
    Option* ptOpt=(Option*)Opt;
    TYPEOPT* opt=(TYPEOPT*)(ptOpt->TypeOpt);

    if ((opt->EuOrAm). Val.V_BOOL==AMER)
        return OK;

    return WRONG;
}

static int MET(Init)(PricingMethod *Met)
{
    static int first=1;

    if (first)
    {
        Met->Par[0].Val.V_INT2=5;
        Met->Par[1].Val.V_INT2=100;
        Met->Par[2].Val.V_RGDOUBLE=0.000001;

        first=0;
    }

    return OK;
}

PricingMethod MET(FD_FMGH)=
{
    "FD_FMGH",
    {{ "Number of grids",INT2,100,ALLOW},{ "
TimeStep",INT2,100,ALLOW} ,{"Epsilon",RGDOUBLE,100,
ALLOW} ,{" ",END,0,FORBID}}},
    CALC(FD_FMGH),

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        {"Price",DOUBLE,100,FORBID},{"Delta1",  
DOUBLE,100,FORBID} , {"Delta2",DOUBLE,100,FORBID} ,  
        {" ",END,0,FORBID}},  
        CHK_OPT(FD_FMGH),  
        CHK_ok,  
        MET(Init)  
};
```

References